

**Optimizing the Video Game Multi-Jump: Player Strategy, AI, and Level Design (by A. M. Broussard, M. E. Malandro, and A. Serreyn) errata**  
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Algorithm 1 was unfortunately mis-formatted in the final version of the paper. Here it is, correctly formatted, using python-ish notation.

Algorithm for computing the jump points  $(x_1, \dots, x_n)$  defining the multi-jump ending at  $(d, \text{hmax}(d))$ .

```
1 #Input: (f1, ..., fn), (c1, ..., cn), d, ε
2 #Output: (x1, ..., xn)
3
4 def NumericalInverse(f, y, a, b, e):
5     g(x) = f(x) - y
6     while True:
7         try:
8             return root(g(x), a, b, e)
9         except RuntimeError (no root): #if there is no root on [a, b]
10            b = b × 10 #then expand the search range to the right
11
12 def OptimalJumpPoints((f1, ..., fn), (c1, ..., cn), d, ε):
13     e = ε
14     def DerivativeCheck((x1, ..., xn)):
15         for i = 1, ..., n:
16             if |f'i(xi) - f'1(x1)| ≥ ε:
17                 return False
18         return True
19     F(x) = x - d + ∑i=2n NumericalInverse(f'i, f'1(x), ci, d, e/n)
20     while True:
21         x1 = root(F(x), c1, d, e/n)
22         for i = 2, ..., n:
23             xi = NumericalInverse(f'i, f'1(x1), ci, d, e/n)
24         if |d - ∑i=1n xi| < ε and DerivativeCheck((x1, ..., xn)):
25             return True
26         else:
27             e = e × 0.1
28
29 return OptimalJumpPoints((f1, ..., fn), (c1, ..., cn), d, ε)
```